

## TTM-200 <br> DIGITAL CONTROLLER



MODE FUNC $\nabla \quad \Delta$
TOHO
TTM-204 (Gray)
 rxw-e04 2040®


TTM-204 (Black)

т1M-207
듀뭉․


| moot | Punc 1 | $\nabla$ | $\Delta$ |
| :--- | :--- | :--- | :--- |



TTM-205

## EZEEEZ:" -



TOHO ELECTRONICS INC.

## nifin TTM-200

Features

Olmprovement of the controllability with new PID algorithm
(1)Time until it is stabilized from a control start is shortened
(2)Loading the jump less control which controls the overshoot after the disturbance
(3) You can chose from three kind of PID control that can be chosen

Full multiple inputs
Established the input specification to be one type of the thermocouple (13 types), the platinum resistance temperature sensor (2 types), voltage ( 5 types) and the electric current (1 type). (Modification of setting with parameter)

## Sampling period

Realized acceleration in 200mS

## Utilizes a liquid crystal display

(1)The indication range has been extended to present 5 columns
(2)Actualized the various indication with 11 segments
(3)Adopted LED to back light

## PV color auto-change

Display color of Process value (PV) can be optionally set from Red, Orange and Green as compare with Setting value (SV).

## OCompact size

Depth is compact size, TTM-204 is only 55mm, and TTM-205, 207 and 209 are also only 65 mm .

## OLoader communication function

The best for the setup work of a parameter
Cable: Option (sold separately)
Software: Free option ---- It can download from our web site

## Abundant output type

Relay contact, SSR-driving, Open collector, Voltage (5 types) and Electric current

## Substantial option function

(1)CT input (Max. of 2 points) (2)Event input (Max. of 4 points) (3)Event output (Max. of 7 points. However, when 7 points are used, you can not use the control output.)

- External standards

We have acquired "CE", "UL" and cUL.
Protection structure (Available only for TTM-204)
Corresponding to "IP66"

## OValve position proportionality control

The function carries out valve position proportionality control without feedback resistance.
Two choices of case colors (Available only for TTM-204)
"Black" or "Gray" choice is possible to preference

## Blind function

The system can be configured so that only specific, selected parameters are displayed from set of parameters.
OSimple timer function (independent three points)
The order of "After the defined time period passes, the control starts or stops" can be controlled by one unit.
Also use by the timer independent is possible. (Event output ON/OFF)

## Priority screen

Without showing a parameter screen, a display and a setup can be performed by indicating a necessary parameter screen on the operation mode screen.
(Maximum of 16 screens)

## -Digital PV filter

Corresponding to the sudden change of input value, it can apply the filter with the software

## - Manual control

A manual output function enables application of various instrumentation systems
Communication function (RS485: An exclusive protocol / MODBUS)
The range extends up to the distance of 500 m , and can connect up to 31 units concurrently.
With one host computer, it can remote consolidate watching "The collection of the data" and "Change of each setting value" at the place where it is far.

## OSoft-start function

When the power supply is turned on, limitation can be put on manipulated value during specific time in PID control.
-Delay timer (Available only ON/OFF control)
It is possible to make the action of control output (Main or auxiliary) delay during specific time (setting). This can be used to protect the freezer.
OLoop Error
This monitors the measured values and operation time in order to detect errors in the control loop.

Front Panel

■Operation flow


| OUT1 | Output1 monitor (It appears when output) |
| :---: | :---: |
| OUT2 | Output2 monitor (It appears when output) |
| OUT3 | Output3 monitor (It appears when output) |
| OUT4 | Output4 monitor (It appears when output) |
| OUT5 | Output5 monitor (It appears when output) |
| OUT6 | Output6 monitor (It appears when output) |
| OUT7 | Output7 monitor (It appears when output) |
| RDY | RDY lamp (It appears in the state of Ready) |
| COM | COM lamp (It blinks during communication) |
| DI1 | DI1 monitor (It appears when DI1 operates) |
| DI2 | DI2 monitor (It appears when DI2 operates) |
| DI3 | DI3 monitor (It appears when DI3 operates) |
| DI4 | DI4 monitor (It appears when DI4 operates) |
| TMR | TIMER lamp (It appears when timer operates) |
| TIME | It appears when the setting is "Timer" |
| ${ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ | It appears when the setting is "Temperature" |
| PV | Measured value indication, Character indication, Timer set-up time indication |
| SV | Set value indication, Operation quantity indication, Timer remaining time indication |
| MODE | Mode key <br> It is used when changing a screen. |
| FUNC | Function key It executes the function that is set |
| - | Up key <br> It is used when making a setting value increase It is used when changing input setting mode |
| $\nabla$ | Down Key <br> It is used when making a setting value decrease <br> It is used when changing parameter screen |
| ※OUT6 is not available for TTM-207. |  |



## Standard specifications

| Input type | Thermocouple | K, J, T, E, , , S, B, , N, U, L, WRes-26, PR40-20, PLII (Input resistance 1M ) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Pt100, JPt100 |  |  |  |
|  | Electric current / voltage | 4 to 20 mADC (Input | sistance 250 ), 0 to | DC, 0 to 5VDC, 1 to 5 | C, 0 to 10VDC, 0 to 10 mVDC (Input resistance 1M $\Omega$ or more) |
| Indication (LCD Indication) | PV/Character indication | LCD indication (with LED back light, luminous colors are Red, Orange and Green)  <br> TTM-204/205 5 digits, height 10 mm <br> TTM-207 5 digits, height 13 mm <br> TTM-209 5 digits, height 20 mm |  |  |  |
|  | SV/Setting indication | $\begin{aligned} & \text { LCD indication (wit } \\ & \text { TTM-204/205 } \\ & \text { TTM-207 } \\ & \text { TTM-209 } \end{aligned}$ | ED back light, lumin digits, height 8 mm digits, height 8 mm digits, height 10 mm | color is Red) |  |
|  | Auxiliary indication part | LCD indication (with <br> TTM-204/205 <br> TTM-207 <br> TTM-209 | ED back light, lumin digit, height 8 mm digit, height 8 mm digit, height 10 mm | color is Green) |  |
|  | Each functional indication | Red (OUT1, OUT2, OUT3, OUT4, OUT5, OUT6, OUT7, DRY, COM, DI1, D12, D13, DI4, TMR) |  |  |  |
|  | PV color auto-change | Luminous color | Red, Orange and Green |  |  |
|  |  | Luminous color <br> change range | Temperature input | 0.0 to 999.9 or 0 to $999\left({ }^{\circ} \mathrm{C}\right)$ |  |
|  |  |  | Analogue input | 0 to 9999 (digit) |  |
| Control | PID <br> (With auto tuning) (With self tuning) | Proportional band (P1) |  | 0.1 to $200.0 \%$ of set limiter span |  |
|  |  | Proportional band side of Output 2 (P2) |  | 0.10 to 10.00 times (Per main control proportional band) |  |
|  |  | Integration time (I) |  | 0 to 3600 seconds (with "0" integral action OFF) |  |
|  |  | Differentiation time ( D ) |  | 0 to 3600seconds (with "0" derivative control action OFF) |  |
|  |  | Proportion cycle ( $\mathrm{T} 1, \mathrm{~T} 2$ ) |  | 0.1 to 120.0 seconds |  |
|  |  | Dead band (DB) |  | Temperature input | -999.9 to 999.9 or -999 to 999 ( ${ }^{\circ} \mathrm{C}$ ) |
|  |  |  |  | Analog input | -9999 to 9999 (digits) \{The decimal point position is the specified position.\} |
|  | ON/OFF | Control sensitivity (C1, C2) |  | Temperature input | 0.0 to 999.9 or 0 to $999\left({ }^{\circ} \mathrm{C}\right.$ ) |
|  |  |  |  | Analog input | 0 to 9999 (digits) \{The decimal point position is the specified position.\} |
|  | Output 1 and 2 Off point | Position selection setting |  | SV unit setting High/Medium/Low |  |
|  |  | Positional setting |  | Temperature input | -999.9 to 999.9 or -999 to $999\left({ }^{\circ} \mathrm{C}\right.$ ) |
|  |  |  |  | Analog input | -9999 to 9999 (digits) \{The decimal point position is a specified position.\} |
| Control output | Relay contact | 250VAC 3A (Resistance load) 1a contact point Minimum load 5VDC 100mA |  |  |  |
|  | SSR-driving voltage | 0 to 12VDC (Load resistance $600 \Omega$ or more) |  |  |  |
|  | Open collector | 24 VDC 100 mA |  |  |  |
|  | Current/voltage | 4 to 20 mADC (Load resistance $600 \Omega$ or less) |  |  |  |
|  | Itage | 0 to 1 VDC ( Load resistance $500 \mathrm{~K} \Omega$ or more), 0 to 5 VDC (Load resistance $1 \mathrm{~K} \Omega$ or more), 1 to 5 VDC (Load resistance $1 \mathrm{~K} \Omega$ or more) |  |  |  |
|  |  | 0 to 10 VDC (Load resistance $1 \mathrm{~K} \Omega$ or more), 0 to 10 mVDC (Load resistance $500 \mathrm{~K} \Omega$ or more) |  |  |  |
| Sampling cycle |  | 0.2 seconds |  |  |  |
| Setting and instruction accuracy <br> (In ambient temperature $23^{\circ} \mathrm{C}$ <br> $\pm 10$ degree) | Thermocouple | K, J, T, E, R, S, B, N |  | Larger one $\pm\left(0.3 \%+1\right.$ digit) of the instruction value or $\pm 2^{\circ} \mathrm{C}\left(23^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}\right)$ <br> However, -100 to $0^{\circ} \mathrm{C}$ is $\pm 3^{\circ} \mathrm{C}$, and -200 to $-100^{\circ} \mathrm{C}$ is $\pm 4^{\circ} \mathrm{C}$. As for $400^{\circ} \mathrm{C}$ or less of B thermocouple there is no stipulation |  |
|  |  | U,L |  | Larger one $\pm\left(0.3 \%+1\right.$ digit) of the instruction value or $\pm 4^{\circ} \mathrm{C}\left(23^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}\right)$ Less than $0^{\circ} \mathrm{C}$ is $\pm 6^{\circ} \mathrm{C}$. |  |
|  |  | WRe5-26 <br> PR40-20 |  | Larger one $\pm\left(0.6 \%+1\right.$ digit) of the instruction value or $\pm 4^{\circ} \mathrm{C}\left(23^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}\right)$ |  |
|  |  |  |  | $\pm 9.4^{\circ} \mathrm{C} \pm 1$ digit. There is no precision stipulation under $800^{\circ} \mathrm{C}$ |  |
|  |  | $\begin{array}{\|l\|} \hline \text { PR40-20 } \\ \hline \text { PLIII } \\ \hline \end{array}$ |  | Larger one $\pm\left(0.3 \%+1\right.$ digit) of the instruction value or $\pm 2^{\circ} \mathrm{C}$ |  |
|  | RTD | $\begin{array}{\|l\|} \hline \text { PLII } \\ \hline \text { Pt100, JPt100 } \\ \hline \end{array}$ |  | Larger one $\pm\left(0.3 \%+1\right.$ digit) of the instruction value or $\pm 0.9^{\circ} \mathrm{C}\left(23^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}\right)$ |  |
|  | Current/voltage | 0 to 1VDC, 0 to 5VDC |  | $\pm 0.3 \% \pm 1$ digit of set limiter span ( $23^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}$ ) |  |
|  |  | 1 to 5VDC, 0 to 10VDC, 4 to 20mADC |  |  |  |
|  |  | 0 to 10 mVDC |  | $\pm 0.5 \% \pm 1$ digit of set limiter span ( $23^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}$ ) |  |
| Memory element |  | EEPROM |  |  |  |
| Input power supply |  | 100 to $240 \mathrm{VAC}(-15 \%,+10 \%), 50 / 60 \mathrm{~Hz}, 24 \mathrm{VAC} / \mathrm{DC} \pm 10 \%, 50 / 60 \mathrm{~Hz}$ |  |  |  |
| Weight |  | TTM-204:120g TTM-205:210g TTM-207:260g TTM-209:300g |  |  |  |
| Power consumption |  | TTM-204 less than 10VA ( 100 to 24VVAC), less than 4W (24VAC/DC), TTM -205/207/209 less than 11VA ( 100 to 24 VVAC ), less than 5 W ( 24 VACDC ) |  |  |  |
| Accessories |  | Simple instruction manual and Attachment (A handling description is sold separately.) |  |  |  |
| Standard Range of surrounding temperature humidity (Compensating range such as precision) |  | $23^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}, 45$ to $75 \% \mathrm{RH}$ |  |  |  |
| Range of use surroundings temperature humidity |  | 0 to $50^{\circ} \mathrm{C}, 20$ to 90\% RH (Avoid dewiness) |  |  |  |
| Range of preservation surroundings temperature humidity |  | -20 to $70^{\circ} \mathrm{C}$ (Avoid dewiness and freezing), 5 to 95\% RH (Avoid dewiness) |  |  |  |
| Function | Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) | Upper limit (MLH1, MLH2) |  | Digital output | MLL1 to 100.0 (\%), MLL2 to 100.0 (\%) |
|  |  |  |  | Analogue output | MLL1 to 110.0 (\%), MLL2 to 110.0 (\%) |
|  |  | Lower limit (MLL1, MLL2) |  | Digital output | 0.0 to MLH1 (\%), 0.0 to MLH2 (\%) |
|  |  |  |  | Analogue output | -10.0 to MLH1 (\%), -10.0 to MLH2 (\%) |
|  | Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variablesetting setting | 0.0 to 549.9 (\%) (Function OFF by 0.0\%) |  |  |  |
|  |  | Digital output | 0.0 to 100.0 (\%) |  |  |
|  |  | Analog output | -10.0 to 110.0 (\%) |  |  |
|  | Setting limiter (SLL, SLH) | Upper limit (SLH) |  | Temperature input | $(\mathrm{SLL}+5.0)$ to SV setting range upper limit, (SLL +5 ) to SV setting range upper limit ( ${ }^{\circ} \mathrm{C}$ ) |
|  |  |  |  | Analogue input | (SLL + 5.0) to SV setting range upper limit (digit) |
|  |  | Lower limit (SLL) |  | Temperature input | SV setting range lower limit to (SLH -5.0), SV setting range lower limit to (SLH-5) ( ${ }^{\circ} \mathrm{C}$ ) |
|  |  |  |  | Control stop, control beginning, manual control, timer1 operation, timer2 operation, and timer3 operation |  |  |  |
|  | Control mode (MD) |  |  |  |  |  |  |
|  | Control types (CNT) | PID type |  | Type A (Normal PID control type) |  |
|  |  |  |  | Type B (Over-shoot protection type) |  |
|  |  |  |  | Type C (External disturbance protection type) |  |
|  |  | Type B mode |  | Over-shoot protection Weak |  |
|  |  |  |  | Over-shoot protection Middle |  |
|  |  |  |  | Over-shoot protectio | Strong |
|  |  | Normal reverse action setting |  | Reverse action |  |
|  |  |  |  | Normal action |  |
|  |  | Tuning type setting |  | Main auto-tuning (Main PID/position proportionality control) |  |
|  |  |  |  | Main self-tuning (Main PID/position proportionality control) |  |
|  |  |  |  | Auxiliary auto-tuning (Main PID/auxiliary PID) |  |
|  |  |  |  | Auxiliary self-tuning (Main PID/auxiliary PID) |  |
|  |  |  |  | Main/auxiliary auto- | uning (Main PID/auxiliary PID) |
|  | Output gain setting (MV1G, MV2G) | 0.0 to 1000.0 (\%) |  |  |  |
|  | PV correction, 0 point setting (PVS) | Temperature input -999.9 to $\left.999.99^{\circ} \mathrm{C}\right)$ |  |  |  |
|  |  | Analog input |  | -9999 to 9999 (digit) |  |
|  | PV correction, gain setting (PVG) | 0.500 to 2.000 (times) |  |  |  |
|  | PV input filter (PD) | 0.0 to 99.9 (seconds) |  |  |  |
|  | Anti reset windup | 0.0 to 110.0 (\%) (Function OFF by $110.0 \%$ setting) |  |  |  |
|  | Manual reset (PBB) | 0.0 to 100.0 (\%) (-100.0 to 100.0 (\%) if there is auxiliary control) |  |  |  |
|  | Loop abnormal time setting | Main control loop abnormal time setting Auxiliary control loop abnormal time setting |  | $\begin{array}{\|l} \hline 0 \text { to } 9999 \text { (seconds) } \\ \hline 0 \text { to } 9999 \text { (seconds) } \\ \hline \end{array}$ |  |
|  |  |  |  |  |  |

## Standard specifications

| Function | Timer driving mode (TMF) | Three points. 0 minute and 00 second to 99 minutes and 59 seconds. 0 hour and 00 minute to 99 hours and 59 minutes. Timer repetition frequency: 0 to 99 times (With 0 unlimited frequency) <br> Accuracy: $\pm(1.5 \%+0.5$ seconds) of setting time |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Function: Auto start, Manual start, Event start, SV start, DI start |  |  |
|  | Delay timer (FDT) | 0 to 99 (minutes) Main/auxiliary common |  |  |
|  | Decimal point movement (DP) | Indication below decimal point. Yes/No |  |  |
|  | Manual control | Manual control is possible. (Balance-less / Bump-less) |  |  |
|  | RUN/READY | Switching of RUN/READY is possible. |  |  |
|  | Blind function | An optional parameter screen can be set up in the non-indication. |  |  |
|  | Auto tuning coefficient (ATG) | 0.1 to 10.0 times |  |  |
|  | Auto tuning sensitivity (ATC) | Temperature input | 0.0 to 999.9 or 0 to $999\left({ }^{\circ} \mathrm{C}\right)$ |  |
|  |  | Analog input 0 to 9999 (digits) |  |  |
|  | Function key | A function key can be chosen from "Figure movement", "MD/ready", "AT start/stop", "Timer start/reset", "Reverse screen turning", "ENT", "Bank change" and "Auto/manual change". Settlement of push time ( 0 to 5 seconds) |  |  |
|  | Priority screen | An optional parameter screen can be indicated in the operation mode. (Maximum of 16 points) |  |  |
|  | Lock function (LOC) | Four modes (OFF, ALL Lock, Operation mode lock, and lock except operation mode) |  |  |
|  | Self-diagnostic function | EEPROM data check (Err0), A/D converter action check (Err1), auto-tuning check (Err2), watch-dog timer equipped |  |  |
|  | Ramp function | Action | When modify SV , set up the SV variation per minute |  |
|  |  | Setting range | Temperature input | 0.0 to $999.9^{\circ} /$ /minute (Ramp function turns OFF by 0 |
|  |  |  | Analog input | 0 to 9999 digit/minute (Ramp function turns OFF by |
|  |  | Setting unit | Temperature input | $0.1{ }^{\circ} \mathrm{C} / \mathrm{minute}$ |
|  |  |  | Analog input | 0.1 digit/minute |
|  | Valve function | Motor stroke time | 0.1 to 999.9 (seconds) |  |
|  |  | Motor drive dead band | 0.0 to 100.0 (second |  |
|  | Initialization mode | Password setup, blind screen one time call setup, setting value backup and set value initialization Since a password is required for this mode when making a setting change, please be sure to keep the password. |  |  |
|  | Bank setting | Setting the parameter of set 1 to 17 (A maximum of 16 points) |  |  |
|  | Soft-start (Main control) | Output setting | MLL1 to MLH1 (\%)00:00 to 99:59 (minutes), Function OFF by 00:00 (minutes) |  |
|  |  | Time setting |  |  |

## Option specifications



## Option Specifications (Continued)

| Remote SV Input | Input Type (Current/Voltage Multi-Input) | 0 to 1VDC, 0 to 5VDC, 1~ | 5VDC, 0 to 10VDC, 4 to 20mADC |
| :---: | :---: | :---: | :---: |
|  | Measurement/Range of Setting | -19999 to + 29999 (deci | nal point can be set at any location) |
|  | Range of Display (Full Scale: Range of FSL2 to FSH2) | 0 to 1VDC, 0 to 5VDC, 0 to 10VDC | High Limit: + 12\% of full scale |
|  |  |  | Low Limit: Maximum of $-2 \%$ of full scale |
|  |  | 1 to 5VDC, 4 to 20mADC | High Limit: + $12 \%$ of full scale |
|  |  |  | Low Limit: $-12 \%$ of full scale |
|  | Resolution | $\pm 0.3 \%$ of full scale +1 digit |  |
|  | Display scaling | High Limit (FSH2): FSL2 to 29999 (digit) |  |
|  | High limit (FSH2)/Low limit (FSL2) | Low Limit (FSL2): -19999 to FSH2 (digit) |  |
|  | Display Resolution Performance | 20000 or less |  |
|  | PV Correction Zero-Point Setting (PVS2) | -9999 to 9999 (digit) |  |
|  | PV Correction Gain Setting (PVG2) | 0.500 to 2.000 (Multiple) |  |
|  | PV Input Filter (PDF2) | 0.0 to 99.9 (seconds) |  |
|  | Local/Remote Switch | Local, remote 1 (scaling with SLL1 and SLH1) |  |
|  |  | Remote 2 (scaling with FSL2 and FSH2) |  |

Input and scale range

| Thermocouple |  | Measurement/measurement range | Indication resolution |
| :---: | :---: | :---: | :---: |
| K | ${ }^{\circ} \mathrm{C}$ | -200.0 to 1372.0 | $1{ }^{\circ} \mathrm{C} / 0.1{ }^{\circ} \mathrm{C}$ |
| J | ${ }^{\circ} \mathrm{C}$ | -200.0 to 1200.0 | $1^{\circ} \mathrm{C} / 0.1^{\circ} \mathrm{C}$ |
| T | ${ }^{\circ} \mathrm{C}$ | -200.0 to 400.0 | $1{ }^{\circ} \mathrm{C} / 0.1{ }^{\circ} \mathrm{C}$ |
| E | ${ }^{\circ} \mathrm{C}$ | -200.0 to 1000.0 | $1^{\circ} \mathrm{C} / 0.1^{\circ} \mathrm{C}$ |
| R | ${ }^{\circ} \mathrm{C}$ | -50.0 to 1768.0 | $1^{\circ} \mathrm{C}$ |
| S | ${ }^{\circ} \mathrm{C}$ | -50.0 to 1768.0 | $1^{\circ} \mathrm{C}$ |
| B | ${ }^{\circ} \mathrm{C}$ | -0.0 to 1800.0 | $1^{\circ} \mathrm{C}$ |
| N | ${ }^{\circ} \mathrm{C}$ | -200.0 to 1300.0 | $1^{\circ} \mathrm{C} / 0.1{ }^{\circ} \mathrm{C}$ |
| U | ${ }^{\circ} \mathrm{C}$ | -200.0 to 400.0 | $1^{\circ} \mathrm{C} / 0.1^{\circ} \mathrm{C}$ |
| L | ${ }^{\circ} \mathrm{C}$ | -200.0 to 900.0 | $1{ }^{\circ} \mathrm{C} / 0.1{ }^{\circ} \mathrm{C}$ |
| WRe5-26 | ${ }^{\circ} \mathrm{C}$ | 0.0 to 2300.0 | $1^{\circ} \mathrm{C}$ |
| PR40-20 | ${ }^{\circ} \mathrm{C}$ | 0.0 to 1880.0 | $1^{\circ} \mathrm{C}$ |
| PLII | ${ }^{\circ} \mathrm{C}$ | 0.0 to 1390.0 | $1{ }^{\circ} \mathrm{C} / 0.1{ }^{\circ} \mathrm{C}$ |


| RTD |  | Measurement/measurement range | Indication resolution |
| :---: | :---: | :---: | :---: |
| $\mathrm{Pt100}(\mathrm{JS} / \mathrm{IEC})$ | ${ }^{\circ} \mathrm{C}$ | -200.0 to 850.0 | $1{ }^{\circ} \mathrm{C} / 0.1^{\circ} \mathrm{C}$ |
| $\mathrm{JPt100}(\mathrm{JS})$ | ${ }^{\circ} \mathrm{C}$ | -200.0 to 510.0 | $1^{\circ} \mathrm{C} / 0.1^{\circ} \mathrm{C}$ |


| Current and voltage | Measurement/measurement range | Indication resolution |
| :---: | :--- | :--- |
| 0 to 1 VDC |  |  |
| 0 to 5 VDC | $\begin{array}{l}-19999 \text { to } 29999 \\ \hline 1 \text { to } 5 \text { VDC }\end{array}$ | $\begin{array}{l}\text { Indication width is less than } \\ 2000 .\end{array}$ | \(\left.\begin{array}{l}A decimal point position can <br>

be changed arbitrarily.\end{array}\right\}\)

## Output connection setting

| Main output |
| :--- |
| Auxiliary output |
| Event output |
| RUN output |
| RDY output |
| Timer1 output |
| Timer1 output at on delay |
| Timer1 output at off delay |
| Timer1 output at on + off delay |
| Timer2 output |
| Timer2 output at on delay |
| Timer2 output at off delay |
| Timer2 output at on + off delay |
| Timer3 output |
| Timer3 output at on delay |
| Timer3 output at off delay |
| Timer3 output at on + off delay |
| Transmission output (When OUT1 and OUT2 are analogue output) |

## Timer drive mode

Start mode

| 1 | Auto start |
| :---: | :--- |
| 2 | Manual start |
| 3 | SV start |
| 4 | DI1 start (Possible to set when option is equipped) |
| 5 | DI2 start (Possible to set when option is equipped) |
| 6 | DI3 start (Possible to set when option is equipped) |
| 7 | DI4 start (Possible to set when option is equipped) |
| 8 | Event 1 start |
| 9 | Event 2 start |
| 10 | Event 3 start (Possible to set when option is equipped) |
| 11 | Event 4 start (Possible to set when option is equipped) |
| 12 | Event 5 start (Possible to set when option is equipped) |
| 13 | Event 6 start (Possible to set when option is equipped) |
| 14 | Event 7 start (Possible to set when option is equipped) |

* Each Start has ON delay/OFF Delay

ON delay: After time-up control stop or event output OFF
OFF delay: After time-up control stop or event output ON

## Point of contact output mode

Event function 1

| Function |  |
| :---: | :---: |
| 4 | No |
| $i$ | Deflection upper and lower limit |
| 2 | Deflection upper limit |
| 3 | Deflection lower limit |
| 4 | Deflection range |
| 5 | Absolute value upper and lower limit |
| 5 | Absolute value upper limit |
| 7 | Absolute value lower limit |
| 8 | Absolute value range |
|  | Addition function |
| $\bigcirc$ | No |
| 1 | Maintenance |
| 2 | Standby sequence |
| 3 | Delay timer |
| 4 | Maintenance + Standby sequence |
| 5 | Maintenance + Delay timer |
| 5 | Standby sequence + Delay timer |
| 7 | Maintenance + Standby sequence + Delay timer |
| Control linkage function |  |
| $\bigcirc$ | All mode |
| i | RUN/MAN mode only |
| 2 | RUN mode only |

Event function 2
(PV abnormal)

| Function |  |
| :---: | :--- |
| $\boldsymbol{Z}$ | No |
| $i$ | Exsist |
| Addition function |  |
| $\boldsymbol{Z}$ | No |
| $i$ | Maintenance |
| $己$ | Delay timer |
| 3 | Maintenance + Delay <br> timer |
| Control linkage function |  |
| $\boldsymbol{Z}$ | All mode |
| $i$ | RUN/MAN mode only |
| $己$ | RUN mode only |

Event function 3
(CT abnormal)

| Function |  |
| :---: | :---: |
| 0 | No |
| i | CT1 abnormal |
| 2 | CT2 abnormal |
| 3 | CT1 abnormal + CT2 abnormal |
| Addition function |  |
| 0 | No |
| i | Maintenance |
| 2 | Delay timer |
| 3 | Maintenance + Delay timer |
| Control linkage function |  |
| 0 | All mode |
| i | RUN/MAN mode only |
| 2 | RUN mode only |

Event function 4
(Loop wire break)

*Event polarity function available

Output functional allotment ( $\bigcirc$ : Allotment is possible, $\times$ : Allotment impossibility)

| Output types | Control output |  | Auxiliary output |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Output1 | Output2 | Output3 | Output4 | Output5 | Output6 | Output7 |
| Main output (Heating) | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Auxiliary output (Cooling) | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Transmission | $\bigcirc$ | $\bigcirc$ | $\times$ | $\times$ | $\times$ | $\times$ | $\times$ |
| Event output | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Timer output | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |

## Wiring

※Please use less than 6 mm width terminal
TTM-204


※ Output 3 and 4 (Terminals 7 to 9 ) are possible to select from either relay output or open collector.
TTM-205, 209

※ Output 3 to 7 (Terminals 19 to 21 and 7 to 12 ) are possible to select from either relay output or open collector.

## TTM-207


※ Output 3 to 5 and 7 (Terminals 11 to 13,7 to 8,23 to 24 ) are possible to select from either relay output or open collector.

## Terminal explanation

| Communication | Please connect the terminal of A and B rightly. <br> (Please use a converter when it is not RE-485) |  |
| :--- | :--- | :--- |
| Output <br> (Right reverse <br> change is possible) | Relay point of <br> contact | C: Common, No: Normal open |
|  | SSR driving | Please connect directly with INPUT+ and - by the <br> side of SSR. |
|  | Transmission, <br> Open collector | Please be connected to polarity of + and - with <br> care |
| CT | Please connect a specified current transformer directly. (CTL-6-P-H) |  |
| PV input/ <br> Al input | Thermocouple | Please be connected to polarity of + and - with <br> care |
|  | Current/ <br> voltage | Please be connected to terminals A, B and b with <br> care |
| DI | COM: Common (The polarity can be switched) |  |
| Al input | Please be connected to polarity of + and - with care |  |

## Dimensions



| Model | a |  | b |  | c | d | A | B | C | D | L |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TTM-204 | 45 | +0.6 <br> -0 | 45 | +0.6 <br> -0 | 60 | 48 | 48 | 48 | 2 | 55 | $(\mathrm{Bxn}-3)$ | +0.6 <br> -0 |
| TTM-205 | 92 | +0.6 <br> -0 | 45 | +0.6 <br> -0 | 120 | 48 | 96 | 48 | 2 | 65 | $(\mathrm{Bxn}-3)$ | +1 <br> -0 |
| TTM-207 | 68 | +0.6 <br> -0 | 68 | +0.6 <br> -0 | 90 | 72 | 72 | 72 | 2 | 65 | $(\mathrm{Bxn}-3)$ | +1 <br> -0 |
| TTM-209 | 92 | +0.6 <br> -0 | 92 | +0.6 <br> -0 | 120 | 96 | 96 | 96 | 2 | 65 | $(\mathrm{Bxn}-3)$ | +1 <br> -0 |

Panel Installation


TTM-205, 207, 209

*For this panel installation, please be careful sufficiently to avoid any of damage.

## Advanced Features

## OPID control by new algorithm


$100^{\circ} \mathrm{C}$



BLIND Function Setting


Content of the above $\star$

1) In BLIND MODE, either $\left\lceil O N \_\right.$\& $\lceil O F F]$ is displayed on under each characters (SV display).
$\lceil O N\lrcorner$ is displayed. 「OFF $\lrcorner$ is not displayed (BLIND).
2) To change characters in BLIND MODE by pressing 「FUNC $\rfloor$ key
3) Power OFF for end of BLIND setting mode.

It is possible not to make the optional picture indicate by the key operation
In addition, please note that only measured value is displayed without displaying a setting value in the case of the usual display when the SV setup screen is turned off.
-OFF point position movement of ON/OFF control
When the OFF point position movement is set to 0 , the OFF point is the set value position.


This is when off point position movement is set up with (+5).

Actually specification, there is no description change as above, but move above equal to $(+5)$ as a position of ON/OFF.
Case it made move on negative side, the OFF point moves to opposite side to description above.

## Timer function

1. In the case of bread baking oven
-Put dough in the oven, and push the start key to the timer.
-The temperature is controlled by the heater and so on for the timer setup time.

- After timer count end control is stopped automatically
(It is used when making control STOP after the timer count ends.)


2. In case of packing machine and industrial machine, which control is started after the completing the preparation of the peripheral device
The count of the timer begins from point that turns on the power supply.
-The control output stops during timer setting time

- The control starts automatically after the timer count ends.
(It is used when making control starts after the timer count ends.)


Communication function

- A connection example with the personal computer

Centralized supervision with the personal computer is possible with the connection like the chart below.


- Loader communication

Host computer

※Loader cable specification
[Appearance and structure]

[Standard and performance]

| USB I/F standard | USB Specification 2.0 Conforming |
| :--- | :--- |
| DTE (Personal computer side) speed | Up to 38400bps |
| Connector specification | Personal computer side: USB |
|  | Temperature Controller side : <br> $\varphi 2.5 \mathrm{~mm}$ Stereo plug |

[Model]
TTM-LOADER

## Digital PV filter

It is the function to realize the CR filter effect on the software by performing primary delay operation to the measured value (PV).
The effect of the filter can be set by the time constant.
(Time constant is the time that the PV value reaches up to about $63 \%$ when the input changes on the step.)


The use of Digital PV filter

1) Removal of high frequency noise --- The influence of a noise when an electric noise joining an input is mitigated.
2) A response can be delayed against the sudden change of the input.

## -Self-tuning PID



## OAuto (RUN) / Manual function

The auto control and the manual control, they can be switched by the front key. Manual operation is the function that is not concerned with the situation of a deviation, but can set up and output the output for control arbitrarily (manipulation variable).

The system can be operated manually in the time of the system trial run and so on, when to check of final control element (a valve, heater, etc.) of operation is performed, when the sensor breaks down by any chance, or when usual control can't be done.

There is the Balance-less Bump-less function, which holds down sudden change of control output when switching the automatic control and manual control mutually. Furthermore, it stops damage on the peripheral equipment by sudden change and the bad influence to a control system. So, you can operate in comfort.


Balance-less Bump-less

## Ramp function

The ramp function is a matter of function made to have inclination against the change in SV (Setting value).
As actual operation, the setting value of a dummy is made to change gradually toward the setting value after changing. Then it controls to the setting value of the dummy. The amount of change for around one minute of SV is set up.
When a rapid change of the control result is not allowed with the characteristic of the control subject, and when the change course (inclination) of the control result becomes important in a control subject, the effect of a ramp function is demonstrated, the effect of the ramp function is demonstrated.
In addition, since only SV is changed, the result expected may not be obtained when it expects great influence to PV (measured value).


## Simultaneous temperature rise function

- Simultaneous temperature rise
-When simultaneous temperature rise control is exerted by multi-channels using the RS-485 communication function, a master and slave are determined beforehand. This permits reaching the respective goal values at the same time regardless of the characteristic of each channel.
The channel, in which the time from the start of control to the reach to the goal value is the longest, is specified as a master. The other channels are specified as slaves.
-The simultaneous temperature rise function is started at the start of run (including the power ON time) or a change of setting value, and is ended when the master reaches the goal value.

- How to use

1. Perform communication protocol settings to the TOHO protocol
2. In the communication changeover setting, set the channel, in which the temperature reaches the goal value latest, to the simultaneous temperature rise master, and then set the other channels to the simultaneous temperature rise slaves.
3. Set the main control sensitivity

During a simultaneous temperature rise, the slave side exerts ON/OFF control for the current temperature of the master. Accordingly, set the sensitivity to a level that does not cause chattering.

## Note: Precautions on use

1. Perform auto tuning for each channel as required
2. When using the simultaneous temperature rise function, do not perform communication with the outside.

## OBank function

8 banks each with 16 setting that can be changed as optional parameter.

A desired state can be reached by adjusting the bank setting, but without modifying the temperature setting or valve of the PID.
This can be done by setting up a parameter for an applicable bank that references the temperature control for one unit.


## ORemote SV

Signals from external sources become the controller parameters.

- Cascade control using remote SV

Cascade control is where the control signal for a single controller is applied to other controllers, and the controller that receives control signals from an external source convert those signals into parameters for control purposes.
As shown in the illustration above, cascade control can be achieved with the use of two controllers.


## Position proportional control

- Position proportional control
- According to the operation amount required for PAD control, the valve opening is changed by outputting an open signal or close signal to the valve on the basis of the valve motor stroke time, so that the flow rate is adjusted, thereby controlling the target temperature. The control can be exerted without feedback resistance.
- The valve motor stroke time means the time from the full opening of the valve till its full closing.



## - Valve motor drive dead band

In position proportional control, the open signal or close signal is output so that the operation amount of the regulator may agree with the opening of the valve. It is necessary to refrain from performing an open/close changeover operation frequently in consideration of the service life of the valve.
A dead band is provided at the open signal/close signal output changeover point.
In this area, both open signal output and close signal output are stopped to reduce frequent open/close changeover operations.

Close signal


- Initial opening after the end of AT

It is possible to set the operation amount just after the end of auto tuning in order to restrict undershoot just after this end.
Example) Response after the end of AT


## OHeating and cooling



## Ordering Information (Model Configurations)

TTM-20
$\begin{array}{cc}\sum_{\text {(1) }}^{4} & \square \\ (2) \\ \end{array}$

| (3) |
| :---: |


(5)

(6)

(7)
$\underbrace{}_{8}$
(8)

| 9 |
| :---: |

(9)

| (10) | \begin{tabular}{\|c|}
\hline
\end{tabular} |
| :--- | :---: |


| (1) | Model |  | 4 | $48 \times 48$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 5 | $96 \times 48$ |  |  |  |
|  |  |  | 7 | $72 \times 72$ |  |  |  |
|  |  |  | 9 | $96 \times 96$ |  |  |  |
| (2) | Case color |  | Q | Black |  |  |  |
|  |  |  | X | Gray (Only selected with 204) |  |  |  |
| (3) | Output 1 |  | N | No |  | J | Voltage 0 to 5VDC |
|  |  |  | R | Relay point of contact |  | F | Voltage 1 to 5VDC |
|  |  |  | P | Voltage for SSR driving |  | G | Voltage 0 to 10VDC |
|  |  |  | A | Open collector |  | I | Current 4 to 20mADC |
|  |  |  | K | Voltage 0 to 1VDC |  | H | Voltage 0 to 10 mVDC |
| (4) | Output 2 |  | N | No |  | J | Voltage 0 to 5VDC |
|  |  |  | R | Relay point of contact |  | F | Voltage 1 to 5VDC |
|  |  |  | P | Voltage for SSR driving |  | G | Voltage 0 to 10VDC |
|  |  |  | A | Open collector |  | I | Current 4 to 20mADC |
|  |  |  | K | Voltage 0 to 1VDC |  | H | Voltage 0 to 10 mVDC |
| (5) | Output 3, 4 |  | A | Open collector | Same for the remote controllers on all models |  |  |
|  |  |  | R | Relay point of contact |  |  |  |
| (6) | Output 5, 6 |  | A | Open collector | Not selectable for 204 207 cannot select output 6 |  |  |
|  |  |  | R | Relay point of contact |  |  |  |
| (7) | Output 7 |  | A | Open collector | Not selectable for 204 <br> Not selectable when W (event 3) has been by 207 |  |  |
|  |  |  | R | Relay point of contact |  |  |  |
| (8) | Al input |  | Y | Remote SV input (voltage/current only) Not selectable for TTV-204 |  |  |  |
| (9) | Option | 204 Selection | ST | CT1, 2 |  |  |  |
|  |  |  | SV | CT1, event 2 |  |  |  |
|  |  |  | UV | Event 1, 2 |  |  |  |
|  |  | 207 Selection | ST | CT1, 2 |  |  |  |
|  |  |  | SV | CT1, event 2 |  |  |  |
|  |  |  | UV | Event 1, 2 |  |  |  |
|  |  |  | STW | CT1, 2 event 3 (output 7 not selectable) |  |  |  |
|  |  |  | SVW | CT1, event 2, 3 (output 7 not selectable) |  |  |  |
|  |  |  | UVW | Event 1, 2, 3 (output 7 not selectable) |  |  |  |
|  |  | 205, 209 Selection | ST | CT1, 2 |  |  |  |
|  |  |  | SV | CT1, event 2 |  |  |  |
|  |  |  | UV | Event 1, 2 |  |  |  |
|  |  |  | SVW | CT1, event 2, 3, 4 |  |  |  |
|  |  |  | UVW | Event 1, 2, 3, 4 |  |  |  |
|  |  |  | STUV | CT1, 2 event 1, 2 |  |  |  |
|  |  |  | STUVW | CT1, 2 event 1, 2, 3, 4 |  |  |  |
| (10) | Communication |  | M | Communications (RS-485) |  |  |  |
| (11) | Power Supply |  |  | 100 to 240V (free power) |  |  |  |
|  |  |  | L | 24VAC/DC |  |  |  |

* Parameters up to output 2 must be selected.
* Specifications apply in accordance with the sequence of selection for output 3 and upwards. Example: TTM-209-Q-PR-RUVW

P: Output 1: SSR drive voltage
R: Output 2: Relay connection
R: Output 3, 4: Relay connection (does not select output 5 and 6) UVW: EV1, 2, 3, 4

* Output 3 and 4 must be selected when output 5 and 6 are required.
* Output 3 and 4 and output 5 and 6 must be selected when output 7 is required. * Option W only consists of event 3 when TTM-207 has been selected. * CTL-6-P-H is added when CT is selected. (2 are added when 2 CTs are selected.) * CT cannot be selected when only analog has been selected for the output.

