





# TTM-200

**DIGITAL CONTROLLER** 











TOHO ELECTRONICS INC.

# CONTROLLER TTM-200

## ■ Features

# Improvement of the controllability with new PID algorithm

①Time until it is stabilized from a control start is shortened

- ②Loading the jump less control which controls the overshoot after the disturbance
- ③You can chose from three kind of PID control that can be chosen

## Full multiple inputs

Established the input specification to be one type of the thermocouple (13 types), the platinum resistance temperature sensor (2 types), voltage (5 types) and the electric current (1 type). (Modification of setting with parameter)

## Sampling period

Realized acceleration in 200mS

## Utilizes a liquid crystal display

- ①The indication range has been extended to present 5 columns
- ②Actualized the various indication with 11 segments
- 3 Adopted LED to back light

## PV color auto-change

Display color of Process value (PV) can be optionally set from Red, Orange and Green as compare with Setting value (SV).

## Compact size

Depth is compact size, TTM-204 is only 55mm, and TTM-205, 207 and 209 are also only 65mm.

## Loader communication function

The best for the setup work of a parameter Cable: Option (sold separately)

Software: Free option ---- It can download from our web site

## Abundant output type

Relay contact, SSR-driving, Open collector, Voltage (5 types) and Electric current

## Substantial option function

①CT input (Max. of 2 points) ②Event input (Max. of 4 points) ③Event output (Max. of 7 points. However, when 7 points are used, you can not use the control output.)

## External standards

We have acquired "CE", "UL" and cUL.

## Protection structure (Available only for TTM-204)

Corresponding to "IP66"

## Valve position proportionality control

The function carries out valve position proportionality control without feedback resistance.

## ●Two choices of case colors (Available only for TTM-204)

"Black" or "Gray" choice is possible to preference

#### Blind function

The system can be configured so that only specific, selected parameters are displayed from set of parameters.

## Simple timer function (independent three points)

The order of "After the defined time period passes, the control starts or stops" can be controlled by one unit.

Also use by the timer independent is possible. (Event output ON/OFF)

## Priority screen

Without showing a parameter screen, a display and a setup can be performed by indicating a necessary parameter screen on the operation mode screen. (Maximum of 16 screens)

## Digital PV filter

Corresponding to the sudden change of input value, it can apply the filter with the software

## • Manual control

A manual output function enables application of various instrumentation systems

## ● Communication function (RS485: An exclusive protocol / MODBUS)

The range extends up to the distance of 500m, and can connect up to 31 units concurrently.

With one host computer, it can remote consolidate watching "The collection of the data" and "Change of each setting value" at the place where it is far.

## Soft-start function

When the power supply is turned on, limitation can be put on manipulated value during specific time in PID control.

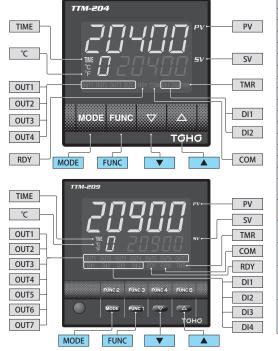
## Delay timer (Available only ON/OFF control)

It is possible to make the action of control output (Main or auxiliary) delay during specific time (setting). This can be used to protect the freezer.

## Loop Error

This monitors the measured values and operation time in order to detect errors in the control loop.

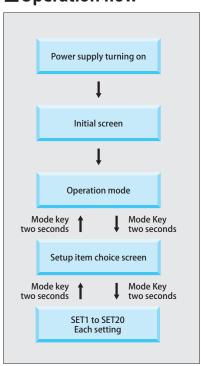
## ■Front Panel



OUT1	Output1 monitor (It appears when output)
OUT2	Output2 monitor (It appears when output)
OUT3	Output3 monitor (It appears when output)
OUT4	Output4 monitor (It appears when output)
OUT5	Output5 monitor (It appears when output)
OUT6	Output6 monitor (It appears when output)
OUT7	Output7 monitor (It appears when output)
RDY	RDY lamp (It appears in the state of Ready)
COM	COM lamp (It blinks during communication)
DI1	DI1 monitor (It appears when DI1 operates)
DI2	DI2 monitor (It appears when DI2 operates)
DI3	DI3 monitor (It appears when DI3 operates)
DI4	DI4 monitor (It appears when DI4 operates)
TMR	TIMER lamp (It appears when timer operates)
TIME	It appears when the setting is "Timer"
°C /°F	It appears when the setting is "Temperature"
PV	Measured value indication, Character
F V	indication, Timer set-up time indication
SV	Set value indication, Operation quantity
	indication, Timer remaining time indication
MODE	Mode key It is used when changing a screen.
FUNC	Function key It executes the function that is set
	Up key
	It is used when making a setting value increase
	It is used when changing input setting mode
	Down Key
▼	It is used when making a setting value decrease
	It is used when changing parameter screen
VOLITE is a	at available for TTM 207

\*OUT6 is not available for TTM-207.

## **■**Operation flow





# ■Standard specifications

Input type	Thermocouple	K, J, T, E, R, S, B, N, U, I	L, WRe5-26, PR40-20, PL	II (Input resistance 1M:	Ω)		
	RTD	Pt100, JPt100					
	Electric current / voltage	4 to 20mADC (Input resistance 250 $\Omega$ ), 0 to 1VDC, 0 to 5VDC, 1 to 5VDC, 0 to 10VDC, 0 to 10mVDC (Input resistance 1M $\Omega$ or more)					
ndication	PV/Character indication	LCD indication (with LED back light, luminous colors are Red, Orange and Green)					
LCD Indication)		TTM-204/205 5 digits, height 10mm					
		TTM-207 5 digits, height 13mm					
	SV/Setting indication	TTM-209 5 digits, height 20mm  LCD indication (with LED back light, luminous color is Red)					
	3V/Setting indication		digits, height 8mm	s color is Rea)			
		TTM-207 5 digits, height 8mm TTM-209 5 digits, height 10mm					
	Auxiliary indication part		LED back light, luminous	s color is Green)			
	Adamary materion part		digit, height 8mm	o color is diccily			
			digit, height 8mm				
		TTM-209 1 digit, neight 8mm					
	Each functional indication	Red (OUT1, OUT2, OU	T3, OUT4, OUT5, OUT6,	OUT7, DRY, COM, DI1, I	DI2, DI3, DI4, TMR)		
	PV color auto-change	Luminous color Red, Orange and Green					
		Luminous color	Temperature input	0.0 to 999.9 or 0 to 9	99 (℃ )		
		change range	Analogue input	0 to 9999 (digit)			
ontrol	PID	Proportional band (P	1)	0.1 to 200.0% of set I	limiter span		
	(With auto tuning)	Proportional band sid	le of Output 2 (P2)	0.10 to 10.00 times (Per main control proportional band)			
	(With self tuning)	Integration time (I)		0 to 3600seconds (w	ith "0" integral action OFF)		
		Differentiation time (	D)	0 to 3600seconds (w	ith "0" derivative control action OFF)		
		Proportion cycle (T1,	T2)	0.1 to 120.0 seconds			
		Dead band (DB)		Temperature input	-999.9 to 999.9 or -999 to 999 (℃ )		
				Analog input	-9999 to 9999 (digits) {The decimal point position is the specified position.}		
	ON/OFF	Control sensitivity (C1	1, C2)	Temperature input	0.0 to 999.9 or 0 to 999 (℃)		
				Analog input	0 to 9999 (digits) {The decimal point position is the specified position.}		
	Output 1 and 2 Off point	Position selection set	ting	SV unit setting High/			
		Positional setting		Temperature input			
				Analog input	-9999 to 9999 (digits) {The decimal point position is a specified position.}		
ontrol output	Relay contact	250VAC 3A (Resistano	ce load) 1a contact point	Minimum load 5VDC			
	SSR-driving voltage		stance 600Ω or more)				
	Open collector	24VDC 100mA					
	Current / voltage		esistance 600Ω or less)				
	Voltage			0 to 5VDC (Load resista	ance 1KΩ or more), 1 to 5VDC (Load resistance 1KΩ or more)		
	1		stance 1KΩ or more), 0				
ampling cycle		0.2 seconds			······································		
etting and instruction	Thermocouple	K, J, T, E, R, S, B, N		Larger one ± (0.3%+	1digit) of the instruction value or ±2°C (23°C ±10°C)		
ccuracy		1,4,4,1,4,1,4,1,1,1		However, -100 to 0°C	is $\pm 3^{\circ}$ C , and -200 to -100°C is $\pm 4^{\circ}$ C . As for 400 °C or less of B thermocouple the		
n ambient temperature 23°C				is no stipulation			
10 degree)		U, L		Larger one $\pm$ (0.3%+1 digit) of the instruction value or $\pm$ 4°C (23°C $\pm$ 10°C ) Less than 0°C is $\pm$ 6°C .			
		WRe5-26			1digit) of the instruction value or ±4°C (23°C ±10°C )		
		PR40-20		±9.4°C±1digit. There is no precision stipulation under 800°C			
		PLII		Larger one ± (0.3%+1digit) of the instruction value or ±2°C			
	RTD	Pt100, JPt100		Larger one $\pm$ (0.3%+1digit) of the instruction value or $\pm$ 0.9°C (23°C $\pm$ 10°C)			
	Current/voltage	0 to 1VDC, 0 to 5VDC		±0.3%±1digit of se	t limiter span (23°C±10°C)		
		1 to 5VDC, 0 to 10VDC, 4 to 20mADC					
		0 to 10mVDC		±0.5%±1digit of se	t limiter span (23°C±10°C )		
Nemory element		EEPROM					
nput power supply		100 to 240VAC (-15%	, +10%), 50/60Hz, 24VA	C/DC±10%, 50/60Hz			
/eight		TTM-204:120g TTM-	-205:210g TTM-207:26	50g TTM-209:300g			
ower consumption					TTM-205/207/209 less than 11VA (100 to 240VAC), less than 5W (24VACDC)		
ccessories		Simple instruction ma	anual and Attachment (	A handling description	is sold separately.)		
tandard Range of surrounding		23°C±10°C, 45 to 75	% RH				
Compensating range such as p							
ange of use surroundings tem	,	0 to 50°C , 20 to 90%					
ange of preservation surround			winess and freezing), 5				
unction	Manipulated variable limiter	Upper limit (MLH1, M	LH2)	Digital output	MLL1 to 100.0 (%), MLL2 to 100.0 (%)		
	(MLH1, MLL1, MLH2, MLL2)	Lauran limit (MILLA MILLA)		Analogue output	MLL1 to 110.0 (%), MLL2 to 110.0 (%)		
		Lower limit (MLL1, MI	LL2)	Digital output	0.0 to MLH1 (%), 0.0 to MLH2 (%)		
				Analogue output	-10.0 to MLH1 (%), -10.0 to MLH2 (%)		
	Upper limit lower limit setting of	0.0 to 549.9 (%) (Fund	ction OFF by 0.0%)				
	manipulated variable change limiter  Abnormal time manipulated variable	District	0.04= 100.0 (01)				
	Abnormal time manipulated variable setting						
		Analog output	-10.0 to 110.0 (%)	Tamma	(CLL + E O) to CV cotting young a server limits (CLL + E) to CV		
	Setting limiter (SLL, SLH)	Upper limit (SLH)		Temperature input	(SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C)		
		Lewes II is (CLL)		Analogue input	(SLL + 5.0) to SV setting range upper limit (digit)		
		Lower limit (SLL)		Temperature input	SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (°C)		
	Control mode (MD)	Combuel et	haninalan	Analogue input	SV setting range lower limit to (SLH - 50) (digit)		
	Control mode (MD)		beginning, manual conf		timer2 operation, and timer3 operation		
	Control types (CNT)	PID type		Type A (Normal PID o	71 -		
				Type B (Over-shoot p			
		Tuna D d.			urbance protection type)		
		Type B mode		Over-shoot protection			
				Over-shoot protection Middle			
		Name of the last		Over-shoot protection Strong			
		Normal reverse action setting		Reverse action			
		L		Normal action			
		Tuning type setting			lain PID/position proportionality control)		
					nin PID/position proportionality control)		
					g (Main PID/auxiliary PID)		
					(Main PID/auxiliary PID)		
				Main/auxiliary auto-1	tuning (Main PID/auxiliary PID)		
	Output gain setting (MV1G, MV2G)	0.0 to 1000.0 (%)					
	PV correction, 0 point setting (PVS)	Temperature input		-999.9 to 999.9 (°C)			
		Analog input		-9999 to 9999 (digit)			
	PV correction, gain setting (PVG)	0.500 to 2.000 (times)	)				
	PV input filter (PD)	0.0 to 99.9 (seconds)					
	Anti reset windup	0.0 to 110.0 (%) (Function OFF by 110.0% setting)					
	Manual reset (PBB)	0.0 to 100.0 (%) (-100.0 to 100.0 (%) if there is auxiliary control)					
	Loop abnormal time setting	Main control loop abnormal time setting 0 to 9999 (seconds)					
	,		abnormal time setting	0 to 9999 (seconds)			
		, , , , , , , , , , , , , , , , , , ,					

# ■Standard specifications

Function	Timer driving mode (TMF)	MF) Three points. 0 minute and 00 second to 99 minutes and 59 seconds. 0 hour and 00 minute to 99 hours and 59 minutes. Timer repetition frequency: 0 to 99 times (With 0 unlimited frequency) Accuracy: £1.5% + 0.5 seconds) of setting time					
		Function: Auto start, Manual start, Event s	tart, SV start, DI start				
	Delay timer (FDT)	0 to 99 (minutes) Main/auxiliary common	0 to 99 (minutes) Main/auxiliary common				
	Decimal point movement (DP)	Indication below decimal point. Yes/No					
	Manual control	Manual control is possible. (Balance-less /	Bump-less)				
	RUN/READY	Switching of RUN/READY is possible.					
	Blind function	An optional parameter screen can be set u	p in the non-indication	i.			
	Auto tuning coefficient (ATG)	0.1 to 10.0 times					
	Auto tuning sensitivity (ATC)	Temperature input	0.0 to 999.9 or 0 to 99	99 (℃)			
		Analog input	0 to 9999 (digits)				
	Function key	A function key can be chosen from "Figure	movement", "MD/read	ly", "AT start/stop", "Timer start/reset", "Reverse screen turning", "ENT", "Bank change"			
		and "Auto/manual change". Settlement of	and "Auto/manual change". Settlement of push time (0 to 5 seconds)				
	Priority screen	An optional parameter screen can be indicated in the operation mode. (Maximum of 16 points)					
	Lock function (LOC)	Four modes (OFF, ALL Lock, Operation mo	Four modes (OFF, ALL Lock, Operation mode lock, and lock except operation mode)				
	Self-diagnostic function	EEPROM data check (Err0), A/D converter action check (Err1), auto-tuning check (Err2), watch-dog timer equipped					
	Ramp function	Action	When modify SV, set up the SV variation per minute				
		Setting range	Temperature input	0.0 to 999.9°C/minute (Ramp function turns OFF by 0.0)			
			Analog input	0 to 9999 digit/minute (Ramp function turns OFF by 0)			
		Setting unit	Temperature input	0.1°C/minute			
			Analog input	0.1 digit/minute			
	Valve function	Motor stroke time	0.1 to 999.9 (seconds)				
		Motor drive dead band	0.0 to 100.0 (seconds)				
	Initialization mode		Password setup, blind screen one time call setup, setting value backup and set value initialization Since a password is required for this mode when making a setting change, please be sure to keep the password.				
	Bank setting	Setting the parameter of set 1 to 17 (A ma	ximum of 16 points)				
	Soft-start (Main control)	Output setting	ing MLL1 to MLH1 (%)				
		Time setting	00:00 to 99:59 (minutes), Function OFF by 00:00 (minutes)				

# **■**Option specifications

Auxiliary output	Relay contact	250VAC 1A (resistan	ce load) 1a contact point			
(2 points)	Open collector	24VDC 100mA	ce loady to contact point			
(Common	Setting range (Upper and Lower	Temperature input	-1999.9 to 2999.9、-19999 to 29999 (°C)			
Terminal)	limit)	Analog input	-19999 to 29999 (digit)			
Sensitivity	-     -					
	Sensitivity		0 to 9999 (digit)			
	Delever's and	Analog input   0 to 9999 (digit)   0 to 9999 (seconds)				
Dilimont	Delay timer		CADV with the Annual Capable along a formula and a standard and a formula December A	A MA		
DI input (Max. 4 points)	Function	Forward action swite	ch (At the time of contact point closing is Forward action)	to/Manual switch (At the time of contact point closing is Manual), Reverse action/		
	1		uto tuning STOP/START (At the time of contact point closing is Auto tuning Start), Timer STOP/START (At the time of contact point closing START)			
	Input specification		point. Active switching is possible at the time of the input.			
	Minimum input time	200mS				
	When ON electric current	Maximum 10mADC				
	When OFF electric current	Maximum 6VDC				
	Terminal permission resistance		333Ω, When OFF: Minimum 500KΩ			
CT input (2 points)	Measurement electric current range	0.0 to 50.0A				
(2 points)	Setting electric current range		resolution 0.1A). However, the function is turning off at 0.0.			
	Setting accuracy	±5% (0.1A or less is				
	Wire break detection		ON time of control output above 300mS			
	Welding detection		OFF time of control output above 300mS			
Communication		Communication		Loader communication		
	Communication standard	RS-485 (1:31)		TTL (1:1)		
	Communication terminal	Terminal stand		Loader communication private terminal		
	Protocol	TOHO exclusive prot	ocol/MODBUS (RTU)/MODBUS (ASCII)	TOHO exclusive protocol/MODBUS (RTU)/MODBUS (ASCII)		
	Direction of information	Half duplex		Half duplex		
	Synchronous system	Asynchronous		Asynchronous		
	Transmission code	ASCII		ASCII		
	Interface	RS-485 (two lines)		TTIL level		
	Transmission speed	2400, 4800, 9600, 19	200, 38400bps	2400, 4800, 9600, 19200, 38400bps		
	Communication distance	500m				
	Response delay time	0 to 250mS		0 to 250mS		
	Communication switch	Writing is impossible	e/Writing is possible/Simultaneous temperature rise master/Si	multaneous temperature rise slave.		
	Character	Start bit: 1 bit fixatio	n	Start bit: 1 bit fixation		
		Stop bit: 1/2 bit		Stop bit: 1/2 bit		
	Data length: 7/8 bit * MODBUS: In case of ASCII 7 bits fixation In case of RTU 8 bits fixation		Data length: 7/8 bit  * MODBUS: In case of ASCII 7 bits fixation In case of RTU 8 bits fixation			
		Parity: No/Even num	ber/Odd number	Parity: No/Even number/Odd number		
		BCC check: No/Yes	BCC Check is invalid	BCC check: No/Yes * In case of MODBUS BCC Check is invalid		
		Address: 1 to 99 stat		Address: 1 to 99 stations * In case of MODBUS 1 to 247 stations		
Transmission output	Functional setting	PV (Process value) output, SV (Setting value) output, MV1 (Main manipulated variable) output, MV2 (Secondary manipulated variable) output. Reciprocal change possibility				
		Temperature input   Scaling low limit to 2999.9 (°C ), scaling low limit to 2999 (°C )				
		Analogue input	Scaling low limit to 29999 (digit)			
		Temperature input 1-1999.9 to scaling high limit (°C ), -1999 to scaling high limit (°C )				
		Analoque input 1-1999 to scaling high limit (digit)				



# **■**Option Specifications (Continued)

Remote SV Input	Input Type (Current/Voltage Multi-Input)	0 to 1VDC, 0 to 5VDC, 1∼	5VDC, 0 to 10VDC, 4 to 20mADC
	Measurement/Range of Setting	-19999 to +29999 (decimal point can be set at any location)	
	Range of Display (Full Scale: Range	0 to 1VDC, 0 to 5VDC,	High Limit: +12% of full scale
	of FSL2 to FSH2)	0 to 10VDC	Low Limit: Maximum of — 2% of full scale
		1 to 5VDC, 4 to 20mADC	High Limit: +12% of full scale
			Low Limit: — 12% of full scale
	Resolution	±0.3% of full scale+1 digit	
	Display scaling	High Limit (FSH2): FSL2 to 29999 (digit)	
	High limit (FSH2)/Low limit (FSL2)	Low Limit (FSL2): — 19999 to FSH2 (digit)	
	Display Resolution Performance	20000 or less	
	PV Correction Zero-Point Setting (PVS2)	-9999 to 9999 (digit)	
	PV Correction Gain Setting (PVG2)	0.500 to 2.000 (Multiple)	
	PV Input Filter (PDF2)	0.0 to 99.9 (seconds)	
	Local/Remote Switch	Local, remote 1 (scaling w	vith SLL1 and SLH1)
		Remote 2 (scaling with FS	SL2 and FSH2)

# ■Input and scale range

Thermocouple		Measurement/measurement range	Indication resolution
K	℃	-200.0 to 1372.0	1℃∕0.1℃
J	°C	-200.0 to 1200.0	1℃∕0.1℃
T	°C	-200.0 to 400.0	1℃∕0.1℃
E	℃	-200.0 to 1000.0	1℃∕0.1℃
R	°C	-50.0 to 1768.0	1℃
S	°C	-50.0 to 1768.0	1℃
В	℃	-0.0 to 1800.0	1℃
N	℃	-200.0 to 1300.0	1℃∕0.1℃
U	°C	-200.0 to 400.0	1℃∕0.1℃
L	°C	-200.0 to 900.0	1℃∕0.1℃
WRe5-26	℃	0.0 to 2300.0	1℃
PR40-20	℃	0.0 to 1880.0	1℃
PLII	°C	0.0 to 1390.0	1℃∕0.1℃

RTD		Measurement/measurement range	Indication resolution	
Pt100 (JIS/IEC)	°C	-200.0 to 850.0	1℃∕0.1℃	
JPt100 (JIS)	°C	-200.0 to 510.0	1℃∕0.1℃	

Current and voltage	Measurement/measurement range	Indication resolution
0 to 1VDC		
0 to 5VDC		
1 to 5VDC	-19999 to 29999 Indication width is less than	A decimal point position can
0 to 10VDC	20000.	be changed arbitrarily.
0 to 10mVDC		
4 to 20mADC		

# ■Output connection setting

Main output
Auxiliary output
Event output
RUN output
RDY output
Timer1 output
Timer1 output at on delay
Timer1 output at off delay
Timer1 output at on + off delay
Timer2 output
Timer2 output at on delay
Timer2 output at off delay
Timer2 output at on + off delay
Timer3 output
Timer3 output at on delay
Timer3 output at off delay
Timer3 output at on + off delay
Transmission output (When OUT1 and OUT2 are analogue output)

## **■**Timer drive mode

## Start mode

1	A. d d d
ı	Auto start
2	Manual start
3	SV start
4	DI1 start (Possible to set when option is equipped)
5	DI2 start (Possible to set when option is equipped)
6	DI3 start (Possible to set when option is equipped)
7	DI4 start (Possible to set when option is equipped)
8	Event 1 start
9	Event 2 start
10	Event 3 start (Possible to set when option is equipped)
11	Event 4 start (Possible to set when option is equipped)
12	Event 5 start (Possible to set when option is equipped)
13	Event 6 start (Possible to set when option is equipped)
14	Event 7 start (Possible to set when option is equipped)

<sup>\*</sup>Each Start has ON delay/OFF Delay

ON delay: After time-up control stop or event output OFF OFF delay: After time-up control stop or event output ON

## **■**Point of contact output mode

## **Event function 1**

	Function
0	No
1	Deflection upper and lower limit
2	Deflection upper limit
2 3 4	Deflection lower limit
Ч	Deflection range
5	Absolute value upper and lower limit
5 7	Absolute value upper limit
7	Absolute value lower limit
8	Absolute value range
	Addition function
0	No
1	Maintenance
2	Standby sequence
0 2 3	Delay timer
Ч	Maintenance + Standby sequence
5	Maintenance + Delay timer
8	Standby sequence + Delay timer
7	Maintenance + Standby sequence + Delay timer
	ontrol linkage function
<i>0</i>	All mode
1	RUN/MAN mode only
5	RUN mode only

# Event function 2 (PV abnormal)

	Function			
0	No			
1	/ Exsist			
	Addition function			
0	No			
- /	Maintenance			
2	Delay timer			
3	Maintenance + Delay			
	timer			
(	Control linkage function			
0	All mode			
1	RUN/MAN mode only			
2	RUN mode only			

# Event function 3 (CT abnormal)

-							
	Function						
0	[] No						
- [	CT1 abnormal						
2	CT2 abnormal						
3	CT1 abnormal + CT2						
١	abnormal						
	Addition function						
0	No						
1	Maintenance						
2	Delay timer						
3	Maintenance + Delay						
٦	timer						
Control linkage function							
0	All mode						
- 1	RUN/MAN mode only						
2	RUN mode only						
0	All mode RUN/MAN mode only						

# Event function 4 (Loop wire break)

Function						
O	No					
1	Exsist					
	Addition function					
0	No					
1	Exsist					

<sup>\*</sup>Event polarity function available

## $\textbf{Output functional allotment} \quad (\bigcirc: \textbf{Allotment is possible}, \ \times: \textbf{Allotment impossibility})$

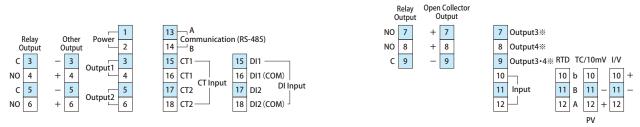
Output types	Control	output	Auxiliary output					
Output types	Output1	Output2	Output3	Output4	Output5	Output6	Output7	
Main output (Heating)	0	0	0	0	0	0	0	
Auxiliary output (Cooling)	0	0	0	0	0	0	0	
Transmission	0	0	×	×	×	×	×	
Event output	0	0	0	0	0	0	0	
Timer output	0	0	0	0	0	0	0	



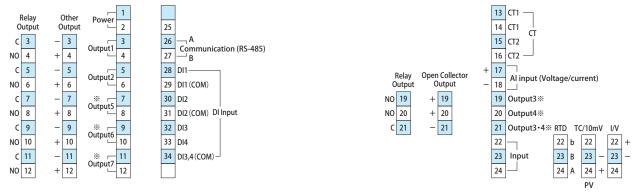
## **■**Wiring

\*Please use less than 6mm width terminal

#### TTM-204

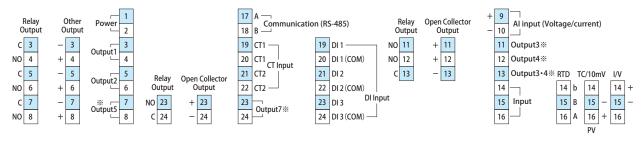


## TTM-205, 209



<sup>\*</sup> Output 3 to 7 (Terminals 19 to 21 and 7 to 12) are possible to select from either relay output or open collector.

## TTM-207

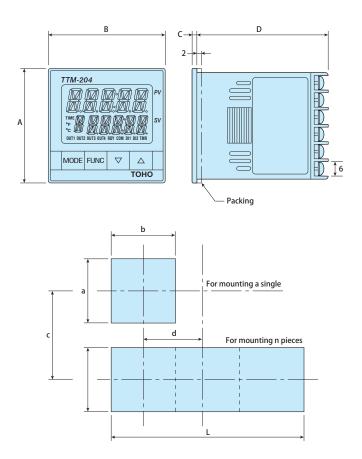


W Output 3 to 5 and 7 (Terminals 11 to 13, 7 to 8, 23 to 24) are possible to select from either relay output or open collector.

## **■**Terminal explanation

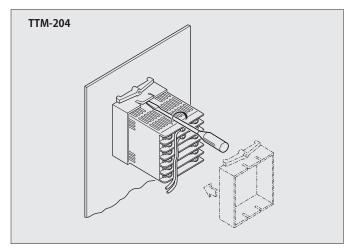
Communication	Please connect the terminal of A and B rightly. (Please use a converter when it is not RE-485)							
Output (Right reverse	Relay point of contact	C: Common, No: Normal open						
change is possible)	SSR driving Please connect directly with INPUT+ and - by side of SSR.							
	Transmission, Open collector Please be connected to polarity of + and - with care							
СТ	Please connect a specified current transformer directly. (CTL-6-P-H)							
PV input/ Al input	Thermocouple Please be connected to polarity of + and - with care							
	Current/ voltage	Please be connected to terminals A, B and b with care						
DI	COM: Common (The polarity can be switched)							
Al input	Please be connected to polarity of + and - with care							

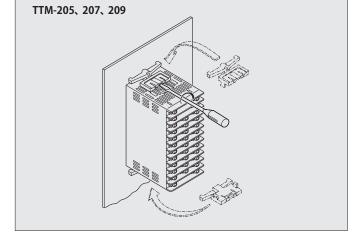
## **■**Dimensions



Model	a		b		С	d	Α	В	С	D	L	
TTM-204	45	+0.6 -0	45	+0.6 -0	60	48	48	48	2	55	(Bxn-3)	+0.6 -0
TTM-205	92	+0.6 -0	45	+0.6 -0	120	48	96	48	2	65	(Bxn-3)	+1 -0
TTM-207	68	+0.6 -0	68	+0.6 -0	90	72	72	72	2	65	(Bxn-3)	+1 -0
TTM-209	92	+0.6 -0	92	+0.6 -0	120	96	96	96	2	65	(Bxn-3)	+1 -0

# **■**Panel Installation



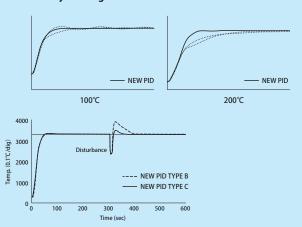


 $<sup>\</sup>ast \mbox{For this panel installation, please be careful sufficiently to avoid any of damage.}$ 

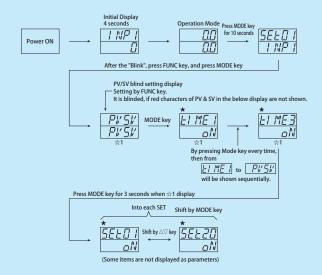


## ■Advanced Features

## ●PID control by new algorithm



## BLIND Function Setting



## Content of the above ★

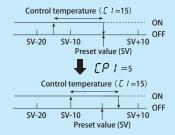
- 1) In BLIND MODE, either <code>「ON」</code> & <code>「OFF]</code> is displayed on under each characters (SV display). <code>「ON」</code> is displayed. <code>「OFF」</code> is not displayed (BLIND).
- 2) To change characters in BLIND MODE by pressing  $\lceil \mathsf{FUNC} \rfloor$  key.
- 3) Power OFF for end of BLIND setting mode.

It is possible not to make the optional picture indicate by the key operation

In addition, please note that only measured value is displayed without displaying a setting value in the case of the usual display when the SV setup screen is turned off.

## ●OFF point position movement of ON/OFF control

When the OFF point position movement is set to 0, the OFF point is the set value position.



This is when off point position movement is set up with (+5).

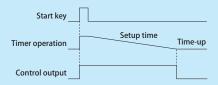
Actually specification, there is no description change as above, but move above equal to (+5) as a position of ON/OFF.

Case it made move on negative side, the OFF point moves to opposite side to description above.

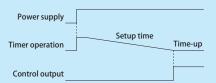
## Timer function

- 1. In the case of bread baking oven
- ●Put dough in the oven, and push the start key to the timer.
- •The temperature is controlled by the heater and so on for the timer setup time.
- ●After timer count end control is stopped automatically

(It is used when making control STOP after the timer count ends.)

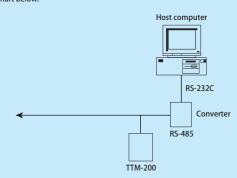


- 2. In case of packing machine and industrial machine, which control is started after the completing the preparation of the peripheral device
  - ●The count of the timer begins from point that turns on the power supply.
  - ●The control output stops during timer setting time
  - The control starts automatically after the timer count ends.
     (It is used when making control starts after the timer count ends.)



## Communication function

 A connection example with the personal computer
 Centralized supervision with the personal computer is possible with the connection like the chart below.



Loader communication



\*Loader cable specification

[Appearance and structure]



## [Standard and performance]

USB I/F standard	USB Specification 2.0 Conforming			
DTE (Personal computer side) speed	Up to 38400bps			
Connector specification	Personal computer side: USB			
	Temperature Controller side : φ 2.5mm Stereo plug			

[Model]

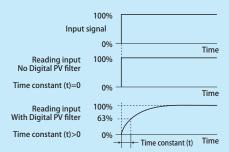
TTM-LOADER

## Digital PV filter

It is the function to realize the CR filter effect on the software by performing primary delay operation to the measured value (PV)

The effect of the filter can be set by the time constant.

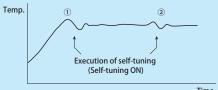
(Time constant is the time that the PV value reaches up to about 63% when the input changes on the step.)



The use of Digital PV filter

- 1) Removal of high frequency noise --- The influence of a noise when an electric noise joining an input is mitigated.
- 2) A response can be delayed against the sudden change of the input.

## Self-tuning PID



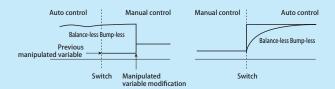
- ①At the time of setting value change ②At the time of the temperature change by disturbance,
- and at the time of hunching generating

## • Auto (RUN) / Manual function

The auto control and the manual control, they can be switched by the front key. Manual operation is the function that is not concerned with the situation of a deviation, but can set up and output the output for control arbitrarily (manipulation variable).

The system can be operated manually in the time of the system trial run and so on, when to check of final control element (a valve, heater, etc.) of operation is performed, when the sensor breaks down by any chance, or when usual control can't be done

There is the Balance-less Bump-less function, which holds down sudden change of control output when switching the automatic control and manual control mutually. Furthermore, it stops damage on the peripheral equipment by sudden change and the bad influence to a control system. So, you can operate in comfort.



Balance-less Bump-less

#### Ramp function

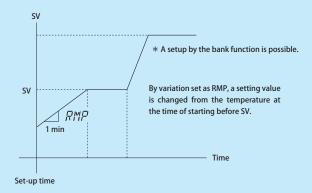
The ramp function is a matter of function made to have inclination against the change in SV (Setting value).

As actual operation, the setting value of a dummy is made to change gradually toward the setting value after changing. Then it controls to the setting value of the dummy.

The amount of change for around one minute of SV is set up.

When a rapid change of the control result is not allowed with the characteristic of the control subject, and when the change course (inclination) of the control result becomes important in a control subject, the effect of a ramp function is demonstrated, the effect of the ramp function is demonstrated.

In addition, since only SV is changed, the result expected may not be obtained when it expects great influence to PV (measured value).



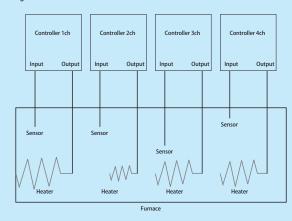
## Simultaneous temperature rise function

#### ■Simultaneous temperature rise

• When simultaneous temperature rise control is exerted by multi-channels using the RS-485 communication function, a master and slave are determined beforehand. This permits reaching the respective goal values at the same time regardless of the characteristic of each channel.

The channel, in which the time from the start of control to the reach to the goal value is the longest, is specified as a master. The other channels are specified as slaves.

• The simultaneous temperature rise function is started at the start of run (including the power ON time) or a change of setting value, and is ended when the master reaches the goal value.



- 1. Perform communication protocol settings to the TOHO protocol.
- 2. In the communication changeover setting, set the channel, in which the temperature reaches the goal value latest, to the simultaneous temperature rise master, and then set the other channels to the simultaneous temperature rise slaves.
- 3. Set the main control sensitivity.

During a simultaneous temperature rise, the slave side exerts ON/OFF control for the current temperature of the master. Accordingly, set the sensitivity to a level that does not cause chattering.

## Note: Precautions on use

- 1. Perform auto tuning for each channel as required.
- 2. When using the simultaneous temperature rise function, do not perform communication with the outside.

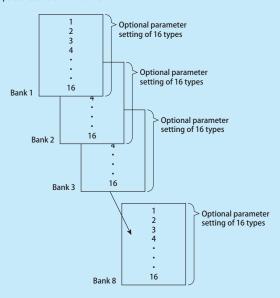


## Bank function

 $8\ banks$  each with  $16\ setting$  that can be changed as optional parameter.

A desired state can be reached by adjusting the bank setting, but without modifying the temperature setting or valve of the PID.

This can be done by setting up a parameter for an applicable bank that references the temperature control for one unit.



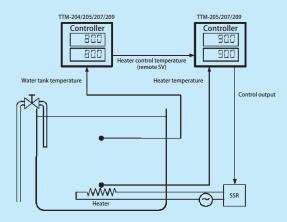
## Remote SV

Signals from external sources become the controller parameters.

## • Cascade control using remote SV

Cascade control is where the control signal for a single controller is applied to other controllers, and the controller that receives control signals from an external source convert those signals into parameters for control purposes.

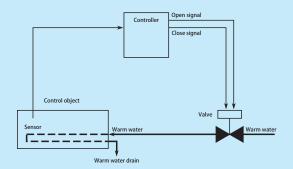
As shown in the illustration above, cascade control can be achieved with the use of two controllers.



## Position proportional control

## ■Position proportional control

- According to the operation amount required for PAD control, the valve opening is changed by outputting an open signal or close signal to the valve on the basis of the valve motor stroke time, so that the flow rate is adjusted, thereby controlling the target temperature. The control can be exerted without feedback resistance.
- The valve motor stroke time means the time from the full opening of the valve till its full closing.



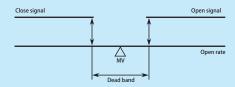
#### · Valve motor drive dead band

In position proportional control, the open signal or close signal is output so that the operation amount of the regulator may agree with the opening of the valve.

It is necessary to refrain from performing an open/close changeover operation frequently in consideration of the service life of the valve.

A dead band is provided at the open signal/close signal output changeover point. In this area, both open signal output and close signal output are stopped to

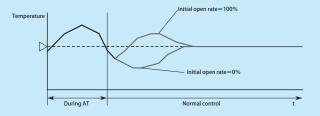
In this area, both open signal output and close signal output are stopped to reduce frequent open/close changeover operations.



## • Initial opening after the end of AT

It is possible to set the operation amount just after the end of auto tuning in order to restrict undershoot just after this end.

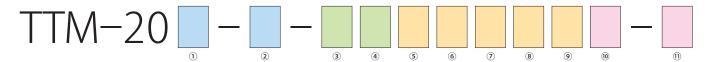
Example) Response after the end of AT



## • Heating and cooling



## **■**Ordering Information (Model Configurations)



(1)	Model		4	48×48							
	Model		5	96×48							
			7	72×72							
			9	96×96							
2	Case color			Black							
			Q X	Gray (Only selected with 204)							
(3)	Output 1		N	No J Voltage 0 to 5VDC							
	output.		R	Relay point of contact		F	Voltage 1 to 5VDC				
			P	Voltage for SSR driving		G	Voltage 0 to 10VDC				
			Α	Open collector		ī	Current 4 to 20mADC				
			K	Voltage 0 to 1VDC	-	Н	Voltage 0 to 10mVDC				
4	Output 2		N	No		J	Voltage 0 to 5VDC				
			R	Relay point of contact		F	Voltage 1 to 5VDC				
			Р	Voltage for SSR driving		G	Voltage 0 to 10VDC				
			A	Open collector		ı	Current 4 to 20mADC				
			K	Voltage 0 to 1VDC		Н	Voltage 0 to 10mVDC				
(5)	Output 3, 4		A	Open collector							
			R	Relay point of contact	Same for the remote controllers on all models						
6	Output 5, 6		Α	Open collector							
			R	Relay point of contact	207 cannot select output 6						
7	Output 7		Α	Open collector	Not selectable for 204						
			R	Relay point of contact Not selectable when W (event 3) has been by 207							
8	Al input		Υ	Remote SV input (voltage/curren	t only) Not selectable fo	r TTV-204					
9	Option 204 Selection		ST	CT1, 2	·						
			SV	CT1, event 2							
			UV	Event 1, 2							
	207 Selection		ST	CT1, 2							
			SV	CT1, event 2							
			UV	Event 1, 2							
			STW	CT1, 2 event 3 (output 7 not selec							
			SVW	CT1, event 2, 3 (output 7 not selection							
			UVW	Event 1, 2, 3 (output 7 not selectable)							
	205, 209 Selection ST			CT1,2							
			SV	CT1, event 2							
			UV	Event 1, 2							
			SVW	CT1, event 2, 3, 4							
			UVW	Event 1, 2, 3, 4							
			STUV	CT1, 2 event 1, 2							
			STUVW	CT1, 2 event 1, 2, 3, 4							
10	Communication		М	Communications (RS-485)							
11)	11) Power Supply			100 to 240V (free power)							
			L	24VAC/DC							

<sup>\*</sup> Parameters up to output 2 must be selected.

 $\star$  Specifications apply in accordance with the sequence of selection for output 3 and upwards.

Example: TTM-209-Q-PR-RUVW

P: Output 1: SSR drive voltage

R: Output 2: Relay connection

R: Output 3, 4: Relay connection (does not select output 5 and 6)

UVW: EV1, 2, 3, 4

- \*Output 3 and 4 must be selected when output 5 and 6 are required.
- \*Output 3 and 4 and output 5 and 6 must be selected when output 7 is required.
- $\star$  Option W only consists of event 3 when TTM-207 has been selected.
- \*CTL-6-P-H is added when CT is selected. (2 are added when 2 CTs are selected.)
- \*CT cannot be selected when only analog has been selected for the output.



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